

Solution of the qc Yamabe equation on a 3-Sasakian manifold and extremals of the Sobolev-Folland-Stein inequality on the quaternionic Heisenberg groups

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based on joint works with Ivan Minchev, Alexander Petkov & Dimitar Vassilev

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The Folland-Stein inequality. $p^* = \frac{pQ}{Q-p}$

Theorem (G.Folland & E.Stein)

Let $\Omega \subset \mathbf{G}$ be an open set in a group of Heisenberg type (Carnot group) of homogeneous dimension Q . For any $1 < p < Q$ there exists $S_p = S_p(\mathbf{G}) > 0$ such that for $u \in C_0^\infty(\Omega)$

$$\left(\int_{\Omega} |u|^{p^*} dH(g) \right)^{1/p^*} \leq S_p \left(\int_{\Omega} |Xu|^p dH(g) \right)^{1/p}.$$

Here, $|Xu|^2 = \sum_{i=1}^m |X_i u|^2$ where X_1, \dots, X_m is a basis of the horizontal space.

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- The Euler-Lagrange equation characterizing the non-negative extremals) (after scaling) is $\sum_{i=1}^m X_i(|Xu|^{p-2} X_i u) = -u^{p^*-1}$.
- When $p = 2$, -the problem reduces to the solvability of the Yamabe equation

$$\sum_{i=1}^m X_i^2 u = -u^{\frac{Q+2}{Q-2}}.$$

- Zero dimensional center - $\mathbf{G} = \mathbb{R}^n$.

The problem can be translated to the standard sphere S^n via the stereographic map - leads to involve Riemannian geometry - the Riemannian Yamabe problem.

Let (M, g) - compact, Riemannian manifold, $2^* = \frac{2n}{n-2}$. If $\bar{g} = u^{4/(n-2)}g$, then

$$4 \frac{n-1}{n-2} \Delta u - \text{Scal} \cdot u = -\overline{\text{Scal}} \cdot u^{2^*-1}.$$

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- The Yamabe equation characterizes the non-negative extremals of the **Yamabe functional**:
 $\Upsilon(u) = \int_M (4 \frac{n-1}{n-2} |\nabla u|^2 + \text{Scal} u^2) dv_g$.

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 $\Upsilon(u) = \int_M (4 \frac{n-1}{n-2} |\nabla u|^2 + \text{Scal} u^2) dv_g$.
- **Yamabe invariant**: $\Upsilon([g]) = \inf\{\Upsilon(u) : \int_M u^{2^*} dv_g = 1, u > 0\}$.

The main idea is to replace the non-linear Yamabe on S^n with a geometrical system of equations which can be solved-namely conformal deformations preserving the Einstein condition -relies on the Obata theorem:

Theorem (Obata)

Let (S^n, g_{st}) be the unit sphere in \mathbb{R}^{n+1} . If g is a Riem. metric, $g = \phi^2 g_{st}$, and $Scal_g = S = \text{const}$, then the metric g is again Einstein.

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Proof Relies on a non-trivial 'divergence-type' formula (Obata).

There is a conceptual proof found by Lee-Parker: $0 = Ric_o^{st} = Ric_o + \frac{n-2}{\phi} (\nabla^2 \phi)_o$. Thus,

$(\nabla^2 \phi)_o = -\frac{\phi}{n-2} Ric_o$. Using $2\nabla^*(Ric_o) = \nabla S = 0$, from the contracted Bianchi and $S=\text{const}$, it follows

$$\text{div } Ric_o(\nabla \phi, \cdot) = -\frac{\phi}{n-2} |Ric_o|^2.$$

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One-dimensional center-The CR Obata

One-dimensional center - (complex) Heisenberg group $\mathbf{G} = \mathbb{C}^n \times \mathbb{R}$.

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$(M^{2n+1}, \theta) \subset \mathbb{C}^{n+1}$ - strongly pseudo-convex CR manifold.

Theorem (D. Jerison & J. Lee: JAMS'88)

If θ is the contact form of a pseudo-Hermitian structure proportional to the standard contact form $\bar{\theta}$ on the unit sphere in \mathbb{C}^{n+1} , $\theta = f\bar{\theta}$ and $Scal_{\theta} = const$, then θ is again pseudo-Einstein.

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Theorem (J. Lee: Am.J.Math.'88)

If $(M, \bar{\theta})$ is pseudo-Einstein, then $\theta = e^{2u}\bar{\theta}$ is pseudo-Einstein iff u is CR-pluriharmonic on M .

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Note that this method does not give all solutions of the CR-Yamabe equation on the unit sphere/complex Heisenberg group while the geometrical approach of Jerison and Lee gives all solutions.

The CR Yamabe problem

The CR-Yamabe problem is: Given a compact strongly pseudo-convex CR manifold $(M^{2n+1}, \theta) \subset \mathbb{C}^{n+1}$ find a smooth function f such that $\bar{\theta} = e^f \theta$ has constant pseudohermitian scalar curvature.

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Theorem (D. Jerison & J. Lee J. Diff. Geom. '87-'89)

- a) $\Upsilon([\theta]) \leq \Upsilon(S^{2n+1})$, where $S^{2n+1} \subset \mathbb{C}^{n+1}$ is the sphere with its standard CR structure. If $\Upsilon([\theta]) < \Upsilon(S^{2n+1})$, then the Yamabe equation has a solution. [D. Jerison & J. Lee '87]
- b) If $n \geq 2$ and M is not locally CR equivalent to S^{2n+1} , then $\Upsilon([\theta]) < \Upsilon(S^{2n+1})$. [D. Jerison & J. Lee '89]

$$Y(\theta_\epsilon) = \begin{cases} Y(S^{2n+1}) (1 - c_n |S(q)|^2 \epsilon^4) + \mathcal{O}(\epsilon^5), & n \geq 2; \\ Y(S^5) (1 - c_2 |S(q)|^2 \epsilon^4 \ln \epsilon) + \mathcal{O}(\epsilon^4), & n = 2. \end{cases}$$

- c) If $n = 1$ or M is locally CR equivalent to S^{2n+1} , then the Yamabe equation has a solution. [R. Yacoub '01, N. Gamara & R. Yacoub, 01]

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S is the Chern-Moser tensor and one of the key point is the use of the Chern-Moser theorem

Theorem (Chern-Moser: Acta Math '74)

A $(2n + 1)$, $n > 1$ -dimensional CR manifold is locally CR-equivalent to the sphere exactly when the Chern-Moser tensor vanishes, $S = 0$.

Three-dimensional center-Quaternionic Heisenberg Group $\mathbf{G}(\mathbb{H})$

- \mathbb{H} -quaternions, $q = t + ix + jy + kz$, where $t, x, y, z \in \mathbb{R}$ and i, j, k satisfy the multiplication rules

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$$\mathbf{G}(\mathbb{H}) = \mathbb{H}^n \times \text{Im}\mathbb{H}, \quad (q, \omega) \in \mathbf{G}(\mathbb{H}),$$

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The homogeneous dimension of $\mathbf{G}(\mathbb{H})$ is $Q = 4n + 6$, $2^* = \frac{2Q}{Q-2} = \frac{2n+3}{n+1}$.

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The 'quaternionic contact Yamabe equation' on $\mathbf{G}(\mathbb{H})$ is

$$\sum_{\alpha=1}^n (T_\alpha^2 + X_\alpha^2 + Y_\alpha^2 + Z_\alpha^2) u = -\frac{n+1}{4(n+2)} u^{2^*-1} \cdot \text{Const.}$$

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Definition

A quaternionic contact (qc) manifold (M, g, \mathbb{Q}) is a $4n + 3$ -dimensional manifold M with a codimension three distribution H locally given as the kernel of a 1-form $\eta = (\eta_1, \eta_2, \eta_3)$ with values in \mathbb{R}^3 . In addition H has an $Sp(n)Sp(1)$ structure, i.e. we have

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- i) *a Riemannian metric g on H and a rank-three bundle \mathbb{Q} consisting of endomorphisms of H locally generated by three almost complex structures l_1, l_2, l_3 on H satisfying the identities of the imaginary unit quaternions, $l_1 l_2 = -l_2 l_1 = l_3$, $l_1 l_2 l_3 = -id|_H$ which are hermitian compatible with the metric $g(l_{s\cdot}, l_{s\cdot}) = g(\cdot, \cdot)$*

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- ii) the following compatibility condition holds*

$$2g(I_s X, Y) = d\eta_s(X, Y), \quad s = 1, 2, 3, \quad X, Y \in H.$$

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Example 3-Sasakian manifolds M : The cone $C = M \times \mathbb{R}$ with the metric $g_{con} = dt^2 + t^2 g$ is a hyperkähler metric.

- Given η (and H) there exists at most one triple of a.c.str. and metric g that are compatible.
- Rotating η we obtain the same qc-structure.
- Conformal transformations $\eta = (\eta_1, \eta_2, \eta_3)$, $\mu \in \mathcal{C}^\infty(M)$, $\mu > 0$, $\Psi \in \mathcal{C}^\infty(M : SO(3))$.

$$\bar{\eta} = \mu \Psi \eta$$

The associated metric \bar{g} to $\bar{\eta}$ on H is conformal to g ,

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Theorem (O. Biquard: Asterisque '99)

Under the above conditions and $n > 1$, there exists a unique supplementary distribution V of H in TM and a linear connection ∇ on M , s.t.,

1. V and H are parallel
2. g and Q are parallel
3. torsion $T(A, B) = \nabla_A B - \nabla_B A - [A, B]$ satisfies
 - $\forall X, Y \in H, \quad T_{X,Y} = -[X, Y]|_V \in V$
 - $\forall \xi \in V, \quad T_\xi := (X \mapsto (T_{\xi,X})_H) \in (\mathfrak{sp}(n) + \mathfrak{sp}(1))^\perp$

- Note: V is generated by the Reeb vector fields $\{\xi_1, \xi_2, \xi_3\}$ defined with the Biquard conditions

$$\eta_s(\xi_k) = \delta_{sk}, \quad (\xi_s \lrcorner d\eta_s)|_H = 0, \quad (\xi_s \lrcorner d\eta_k)|_H = -(\xi_k \lrcorner d\eta_s)|_H.$$

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- If the dimension of M is seven, $n = 1$, the above conditions do not always hold. Duchemin shows that if we assume, in addition, the existence of Reeb vector fields as above, then there is a connection as before. Henceforth, by a qc structure in dimension 7 we shall mean a qc structure satisfying the Reeb conditions

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- The Biquard connection is invariant under rotations and homotheties, i.e. the forms $\bar{\eta} = a\Psi\eta$, $\Psi \in SO(3)$, $a = \text{const.}$ have the same Biquard connection.

- Contact 3-form on the Quaternionic Heisenberg group $\mathbf{G}(\mathbb{H})$.

$\tilde{\Theta} = (\tilde{\Theta}_1, \tilde{\Theta}_2, \tilde{\Theta}_3) = \frac{1}{2} (d\omega - q \cdot d\bar{q} + dq \cdot \bar{q})$ or

$$\tilde{\Theta}_1 = \frac{1}{2} dx - x^\alpha dt^\alpha + t^\alpha dx^\alpha - z^\alpha dy^\alpha + y^\alpha dz^\alpha$$

$$\tilde{\Theta}_2 = \frac{1}{2} dy - y^\alpha dt^\alpha + z^\alpha dx^\alpha + t^\alpha dy^\alpha - x^\alpha dz^\alpha$$

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- $(\mathbf{G}(\mathbb{H}), \tilde{\theta})$ - the flat model.

- 3-Sasakian sphere: Contact 3-form on the sphere $S^{4n+3} = \{|q|^2 + |p|^2 = 1\} \subset \mathbb{H}^n \times \mathbb{H}$,

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- Identify $\mathbf{G}(\mathbb{H})$ with the boundary Σ of a Siegel domain in $\mathbb{H}^n \times \mathbb{H}$,

$$\Sigma = \{(q', p') \in \mathbb{H}^n \times \mathbb{H} : \operatorname{Re} p' = |q'|^2\},$$

by using the map $(q', \omega') \mapsto (q', |q'|^2 - \omega')$.

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- $\mathcal{C}^* \tilde{\Theta} = \frac{1}{2|1+p|^2} \lambda \tilde{\eta} \bar{\lambda}$, λ -unit quaternion (eg. of *conformal quaternionic contact map*).

Curvature of a Quaternionic Contact Structure

- curvature: $R(A, B)C = [\nabla_A, \nabla_B]C - \nabla_{[A, B]}C$, $R(A, B, C, D) = g(R(A, B)C, D)$;
- qc-Ricci tensor: $Ric(X, Y) = tr_H\{Z \mapsto \mathfrak{R}(Z, X)Y\} = R(e_a, X, Y, e_a)$ for $e_a, X, Y \in H$
- qc-Ricci 2-forms $\rho_s(X, Y) = R(X, Y, e_a, I_s e_a)$
- qc-scalar curvature: $Scal = tr_H Ric = Ric(e_a, e_a)$.
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Theorem (I/ Vasilev: J.Math. Pure Appl.'2010)

The following tensors

- $R(X, Y, Z, V) - R(Z, V, X, Y)$
- $4R_{[-1]}(X, Y, Z, V) = 3R(X, Y, Z, V) - R(I_1 X, I_1 Y, Z, V) - R(I_2 X, I_2 Y, Z, V) - R(I_3 X, I_3 Y, Z, V)$
- $R(\xi_i, X, Y, Z)$
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are determined by the (horizontal!) torsion, $T_{\xi_j}, j = 1, 2, 3$ and the qc scalar curvature $Scal$.

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Corollary

A QC manifold is locally isomorphic to the quaternionic Heisenberg group exactly when the curvature of the Biquard connection restricted to H vanishes, $R|_H = 0$.

Conformal transformations

$\eta = (\eta_1, \eta_2, \eta_3)$, $\mu \in \mathcal{C}^\infty(M)$, $\mu > 0$, $\Psi \in \mathcal{C}^\infty(M : SO(3))$.

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Lemma (O. Biquard: Asterisque '99)

If $\bar{\eta} = u^{4/(Q-2)} \eta$, then

$$4 \frac{Q+2}{Q-2} \Delta u - u \text{Scal} = -u^{2^*-1} \overline{\text{Scal}},$$

where $\Delta u = \text{tr}_H(\nabla du)$, $Q = 4n + 6$, $2^* = 2Q/(Q-2)$.

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The qc-Yamabe problem: Find solutions to

$$4 \frac{Q+2}{Q-2} \Delta u - u \text{Scal} = -u^{2^*-1} \overline{\text{Scal}}, \quad \overline{\text{Scal}} = \text{const}.$$

- Yamabe functional is

$$\Upsilon(u) = \int_M \left(4 \frac{Q+2}{Q-2} |\nabla_H u|^2 + \text{Scal} u^2 \right) dv_g.$$

- The Yamabe invariant is the infimum

$$\Upsilon([\eta]) = \inf_u \{ \Upsilon(u) : \int_M u^{2^*} dv_g = 1, u > 0 \}.$$

Theorem (1. I/ I. Minchev, D. Vassilev' 2015)

Let $\tilde{\eta} = \frac{1}{2h}\eta$, $\tilde{\eta}$ standard quaternionic contact structure on the 3-Sasakian sphere of dimension $4n + 3$. If η has constant qc-scalar curvature, then up to a multiplicative constant η is obtained from $\tilde{\eta}$ by a conformal quaternionic contact automorphism

$$\phi \in \text{Diff}(M), \quad \eta = \phi^* \tilde{\eta} = \mu \Psi \tilde{\eta}, \quad \Psi \in \mathcal{C}^\infty(M : SO(3)),$$

The qc-Yamabe equation, the main result

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Theorem 1 shows, in particular, the following

Corollary

If Φ satisfies the qc Yamabe equation on the quaternionic Heisenberg group $\mathbf{G}(\mathbb{H})$,

$$\frac{4(Q+2)}{Q-2} \Delta_{\tilde{\Theta}} \Phi = -S_{\Theta} \Phi^{2^*-1},$$

for some constant S_{Θ} , then up to a left translation the function $\Phi = (2h)^{-(Q-2)/4}$ and h is given by

$$h(q, \omega) = c_0 \left[(\sigma + |q + q_0|^2)^2 + |\omega + \omega_0 + 2 \text{Im } q_0 \bar{q}|^2 \right], \quad (1)$$

for some fixed $(q_0, \omega_0) \in \mathbf{G}(\mathbb{H})$ and constants $c_0 > 0$ and $\sigma > 0$.

Furthermore, the qc-scalar curvature of Θ is $S_{\Theta} = 128n(n+2)c_0\sigma$.

The Folland-Stein inequality on quaternionic Heisenberg group

Theorem 1 allows the determination of **all** solutions of the qc-Yamabe problem on the sphere and on the quaternionic Heisenberg group. As a consequence of Theorem 1 we obtain that all solutions to the qc Yamabe equation are given by the functions which realize the equality case of the L^2 Folland-Stein inequality. Thus, we confirm the following result

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Theorem (I/, I. Minchev, D. Vassilev: Ann. Sc. Norm Super. Pisa'12)

a) Let $\mathbf{G}(\mathbb{H}) = \mathbb{H}^n \times \text{Im } \mathbb{H}$ be the quaternionic Heisenberg group. The best constant in the L^2 Folland-Stein embedding inequality is

$$S_2 = \frac{[2^{-2n} \omega_{4n+3}]^{-1/(4n+6)}}{2\sqrt{n(n+1)}},$$

where $\omega_{4n+3} = 2\pi^{2n+2}/(2n+1)!$ is the volume of the unit sphere $S^{4n+3} \subset \mathbb{R}^{4n+4}$. The non-negative extremals are given by the functions of the form

$$F = c_0 \left[(\sigma + |q|^2)^2 + |\omega|^2 \right]. \quad (2)$$

Any other non-negative extremal is obtained from F by translations $\tau_{(q_0, \omega_0)} F = F(q_0 + q, \omega_0 + \omega)$ and dilations $F_\lambda = \lambda^4 F(\lambda q, \lambda^2 \omega)$, $\lambda > 0$.

These are all solutions to the qc-Yamabe equation on the quaternionic Heisenberg group $\mathbf{G}(\mathbb{H})$.

b) The qc Yamabe constant of the standard qc structure of the sphere is

$$\lambda(S^{4n+3}, [\tilde{r}]) = 16 n(n+2) [((2n)!) \omega_{4n+3}]^{1/(2n+3)}. \quad (3)$$

Main strategy: Replace the non-linear Yamabe equation on $G(\mathbb{H})$ with a geometrical system which can be solved. Use Cayley to transform the problem to the 3-Sasakian sphere and use compactness.

The first observation is:

Theorem (I/, I. Minchev, D. Vassilev: MemAMS'14, Math.Res.Lett.15)

If M is qc-Einstein then $Scal=const.$

Hint: Try to replace the Yamabe equation with conformal deformations preserving the qc-Einstein condition.

The Torsion Tensor. $T_{\xi_j} = T_{\xi_j}^0 + I_j U$, $U \in \Psi_{[3]}$.

$T_{\xi_j}^0$ -symmetric, $I_j U$ -skew-symmetric.

Biquard shows T_{ξ} is completely trace-free.

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Define $T^0 = T_{\xi_1}^0 I_1 + T_{\xi_2}^0 I_2 + T_{\xi_3}^0 I_3 \in \Psi_{[-1]}$. We have

$$\text{Ric} = (2n + 2)T^0 + (4n + 10)U + \frac{\text{Scal}}{4n}g.$$

$(M^{4n+3}, g, \mathbb{Q})$ is qc-Einstein manifold iff the torsion of the Biquard connection is identically zero.

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3-Sasakian manifold: M^{4n+3} is 3-Sasaki if its cone is hyperkähler of signature $(4n+3,0)$ -positive 3-Sasaki, or $(4n,3)$ -negative 3-Sasaki:

$C = M^{4n+3} \times \mathbb{R}^+$, $g_{con} = t^2 g + \epsilon dt^2$, $\text{Hol}(g_{con}) \in \text{Sp}(n+1) \text{ or } \text{Sp}(n, 1)$. If J_1, J_2, J_3 are the three complex structures on C then $\xi_s = J_s \frac{\partial}{\partial t}$ are the Reeb vector fields of the qc-structure.

The torsion of Biquard connection vanishes, $T_\xi = 0$ and any 3-Sasakian manifold is qc-Einstein.

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$C = M^{4n+3} \times \mathbb{R}^+$, $g_{con} = t^2 g + \epsilon dt^2$, $\text{Hol}(g_{con}) \in \text{Sp}(n+1) \text{ or } \text{Sp}(n, 1)$. If J_1, J_2, J_3 are the three complex structures on C then $\xi_s = J_s \frac{\partial}{\partial t}$ are the Reeb vector fields of the qc-structure.

The torsion of Biquard connection vanishes, $T_\xi = 0$ and any 3-Sasakian manifold is qc-Einstein.

Theorem (I. Minchev, D. Vassilev: MemAMS'14, Math. Res.Lett. '15)

Let $(M^{4n+3}, g, \mathbb{Q})$ be a QC manifold. Suppose $\text{Scal} \neq 0$. The next conditions are equivalent:

- i) $(M^{4n+3}, g, \mathbb{Q})$ is qc-Einstein manifold;
- ii) M is locally 3-Sasakian (positive if $\text{Scal} > 0$, negative if $\text{Scal} < 0$): locally there exists a matrix $\Psi \in C^\infty(M : \text{SO}(3))$, s.t., $(\text{sign}(\text{Scal}) \frac{16n(n+2)}{\text{Scal}} \Psi \cdot \eta, \mathbb{Q})$ is 3-Sasakian (positive or negative);

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Let $(M, \bar{\eta})$ be a compact locally 3-Sasakian qc manifold of qc-scalar curvature $16n(n+2)$.

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The proof of Theorem 2 consists of two steps.

- The first step is a divergence formula which shows that if $\bar{\eta}$ is of constant qc-curvature and is qc-conformal to a locally 3-Sasakian manifold, then $\bar{\eta}$ is also a locally 3-Sasakian manifold.

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- For the proof of the second part of Theorem 2 we show that the smooth function f involved in our divergence formula is an eigenfunction of the sub-Laplacian with the smallest eigenvalue $4n$, thus showing a geometric nature of f , and then use the characterization of the 3-Sasakian sphere by its first eigenvalue of the sub-Laplacian among all locally 3-Sasakian manifolds.

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Theorem (I/A. Petkov, D. Vassilev: Nonlinear Anal'13, J.Geom.Anal.'14, J.Spectral Theory'16)

Let (M, g, \mathbb{Q}) be a compact locally 3-Sasakian manifold of dimension $4n+3$ with qc Ricci tensor $Ric = 4(n+2)g$. Then, the first positive eigenvalue λ of the sub-Laplacian Δ satisfies the equality

$$\lambda = 4n \tag{4}$$

iff the qc manifold (M, g, \mathbb{Q}) is qc-homothetic to the unit $(4n+3)$ -dimensional 3-Sasakian sphere.

Recall that

$$Ric = (2n + 2)T^0 + (4n + 10)U + \frac{Scal}{4n}g$$

The components of the torsion tensor transform according to the following formulas: if $\bar{\eta} = \frac{1}{2h}\eta$

- $\bar{T}^0(X, Y) = T^0(X, Y) + h^{-1} [\nabla dh]_{[sym][-1]}$, where the symmetric part is given by

$$[\nabla dh]_{[sym]}(X, Y) = \nabla dh(X, Y) + \sum_{s=1}^3 dh(\xi_s) \omega_s(X, Y).$$

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- $\bar{U}(X, Y) = U(X, Y) + (2h)^{-1} [\nabla dh - 2h^{-1} dh \otimes dh]_{[3][0]}$
or if $f = \frac{1}{2h}$, $\bar{\eta} = f\eta$, then

$$\bar{U}(X, Y) = U(X, Y) - (2f)^{-1} [\nabla df]_{[3][0]}.$$

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Theorem (I/ I. Minchev, D. Vassilev: Mem AMS '14)

Let $\Theta = \frac{1}{2h}\tilde{\Theta}$ be a conformal deformation of the standard qc-structure $\tilde{\Theta}$ on the quaternionic Heisenberg group $\mathbf{G}(\mathbb{H})$. If Θ is also qc-Einstein, then up to a left translation the function h is given by

$$h = c \left[(1 + \nu |q|^2)^2 + \nu^2 (x^2 + y^2 + z^2) \right],$$

where c and ν are positive constants. All functions h of this form have this property.

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The problem is to show that these are all solutions to the Yamabe equation on $\mathbf{G}(\mathbb{H})$ - we need Obata type theorem Using Cayley we translate the problem to the sphere which is compact and can apply the horizontal divergence formula:

Proposition

Let (M^{4n+3}, η, g_H) be a compact closed manifold with a contact quaternionic structure and σ a horizontal 1-form, $\sigma \in \Lambda^1(H)$. Then we have

$$\int_M (\nabla^* \sigma) \eta_1 \wedge \eta_2 \wedge \eta_3 \wedge \omega_1^{2n} = 0,$$

where $\nabla^* \sigma = -(\nabla \sigma)(e_\alpha; e_\alpha)$ and $\{e_\alpha\}_\alpha$ is an ONB frame on H , $\alpha = 1, \dots, 4n$.

Theorem (I/ I. Minchev, D. Vassilev, 2015)

Suppose (M^{4n+3}, η) is a quaternionic contact structure conformal to a 3-Sasakian structure $(M^{4n+3}, \bar{\eta})$, $\tilde{\eta} = \frac{1}{2h} \eta$. If $\text{Scal}_\eta = \text{Scal}_{\tilde{\eta}} = 16n(n+2)$, then with f given by

$$f = \frac{1}{2} + h + \frac{1}{4} h^{-1} |\nabla h|^2, \quad \text{we have} \quad (5)$$

$$\begin{aligned} \nabla^* \left(f(D + E) + \sum_{s=1}^3 dh(\xi_s) I_s E + \sum_{s=1}^3 dh(\xi_s) F_s + 4 \sum_{s=1}^3 dh(\xi_s) I_s A_s - \frac{10}{3} \sum_{s=1}^3 dh(\xi_s) I_s A \right) \\ = \left(\frac{1}{2} + h \right) \left(|T^0|^2 + |\mathbf{E}|^2 \right) + 2h |\mathbb{D} + \mathbb{E}|^2 + h \langle QV, V \rangle. \quad (6) \end{aligned}$$

Here, Q is a 7 by 7 positive definite matrix, $V = (E, D_1, D_2, D_3, A_1, A_2, A_3)$,

$$A_i = l_i[\xi_j, \xi_k], \quad A = A_1 + A_2 + A_3$$

$$D_s(X) = -\frac{1}{2h} \left[T^0(X, \nabla h) + T^0(l_s X, l_s \nabla h) \right], \quad F_s(X) = -h^{-1} T^0(X, l_s \nabla h)$$

$$E(X) = \frac{h^{-2}}{4} \left[\nabla^2 h(X, \nabla h) + \sum_{s=1}^3 \nabla^2 h(l_s X, l_s \nabla h) + \left(-2 + 4h - 3h^{-1} |\nabla h|^2 \right) dh(X) \right].$$

$$\begin{aligned} \mathbb{D}(X, Y, Z) = & -\frac{h^{-1}}{8} \left[dh(X) T^0(Y, Z) + dh(Y) T^0(X, Z) \right. \\ & \left. + \sum_{s=1}^3 dh(l_s X) T^0(l_s Y, Z) + \sum_{s=1}^3 dh(l_s Y) T^0(l_s X, Z) \right] \quad (7) \end{aligned}$$

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$$Q := \begin{bmatrix} \frac{5}{2} & -\frac{1}{2} & -\frac{1}{2} & -\frac{1}{2} & -2 & -2 & -2 \\ -\frac{1}{2} & \frac{5}{2} & -\frac{1}{2} & -\frac{1}{2} & \frac{10}{3} & -\frac{2}{3} & -\frac{2}{3} \\ -\frac{1}{2} & -\frac{1}{2} & \frac{5}{2} & -\frac{1}{2} & -\frac{2}{3} & \frac{10}{3} & -\frac{2}{3} \\ -\frac{1}{2} & -\frac{1}{2} & -\frac{1}{2} & \frac{5}{2} & -\frac{2}{3} & -\frac{2}{3} & \frac{10}{3} \\ -2 & \frac{10}{3} & -\frac{2}{3} & -\frac{2}{3} & \frac{22}{3} & -\frac{2}{3} & -\frac{2}{3} \\ -2 & -\frac{2}{3} & \frac{10}{3} & -\frac{2}{3} & -\frac{2}{3} & \frac{22}{3} & -\frac{2}{3} \\ -2 & -\frac{2}{3} & -\frac{2}{3} & \frac{10}{3} & -\frac{2}{3} & -\frac{2}{3} & \frac{22}{3} \end{bmatrix}$$

with eigenvalues 1 , $\frac{9}{2} \pm \frac{\sqrt{73}}{2}$ and $\frac{11}{2} \pm \frac{\sqrt{89}}{2}$.

For the first step of the proof of Theorem 2, integrate the divergence formula and then use the divergence theorem to see that the integral of the left-hand side is zero. Thus, the right-hand side vanishes as well, which shows that the quaternionic contact structure $\bar{\eta}$ has vanishing torsion, i.e., it is also qc-Einstein.

Sketch of Proof of the second part of Theorem 2

Recall that a vector field Q on a qc manifold (M, η) is a *qc vector field* if its flow preserves the horizontal distribution $H = \ker \eta$.

$$\mathcal{L}_Q \eta = (\nu I + O) \cdot \eta,$$

where ν is a smooth function and $O \in \mathfrak{so}(3)$ is a matrix valued function with smooth entries.

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$$\mathcal{L}_Q g = \nu g, \quad \mathcal{L}_Q I = O \cdot I, \quad I = (I_1, I_2, I_3)^t, \quad \nu = \frac{1}{2n} \nabla^* Q_H.$$

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Lemma (I/ I. Minchev, D. Vassilev, 2015)

For any qc-vector field on (M, η) we have the formula

$$\Delta(\nabla^* Q_H) = -\frac{n}{2(n+2)} Q(\text{Scal}) - \frac{\text{Scal}}{4(n+2)} \nabla^* Q_H.$$

Let (M, η) and $(M, \bar{\eta})$ be qc-Einsten manifolds with equal qc-scalar curvatures $16n(n+2)$. If η and $\bar{\eta}$ are qc conformal to each other, $\bar{\eta} = \frac{1}{2h} \eta$ for some smooth positive function h , then

$$Q = \frac{1}{2} \nabla f + \sum_{s=1}^3 dh(\xi_s) \xi_s \tag{9}$$

is a qc vector field on M , where the function f appears in the divergence formula.

Proof of the second part of Theorem 2

Consider the qc vector field Q . The function $\phi = \frac{1}{2}\Delta f$ is either an eigenfunction of the sub-Laplacian with eigenvalue $-4n$, $\Delta\phi = -4n\phi$, or it vanishes identically and $f = \text{const}$. In the first case, using the quaternionic contact version of the Lichnerowicz-Obata eigenfunction sphere theorem we conclude that (M, η) is the 3-Sasakian sphere.

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These considerations provide also a certain geometric insight for the mysterious function f in the divergence formula. In fact, up to an additive constant, the mysterious function f is the unique function on M for which $Q_H = \frac{1}{2}\nabla f$ is the horizontal part of a qc vector field Q with vertical part $Q_V = dh(\xi_s)\xi_s$, $Q = Q_H + Q_V$.

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Remarkably, the same situation occur in the CR case: the mysterious function in the Jerison-Lee divergence formula is the unique function on M for which $Q_H = \frac{1}{2}\nabla f$ is the horizontal part of a CR-vector field Q with vertical part $Q_V = dh(\xi)\xi$, $Q = Q_H + Q_V$. This provides geometric insight for the mysterious function f in the Jerison-Lee divergence formula from 1988.